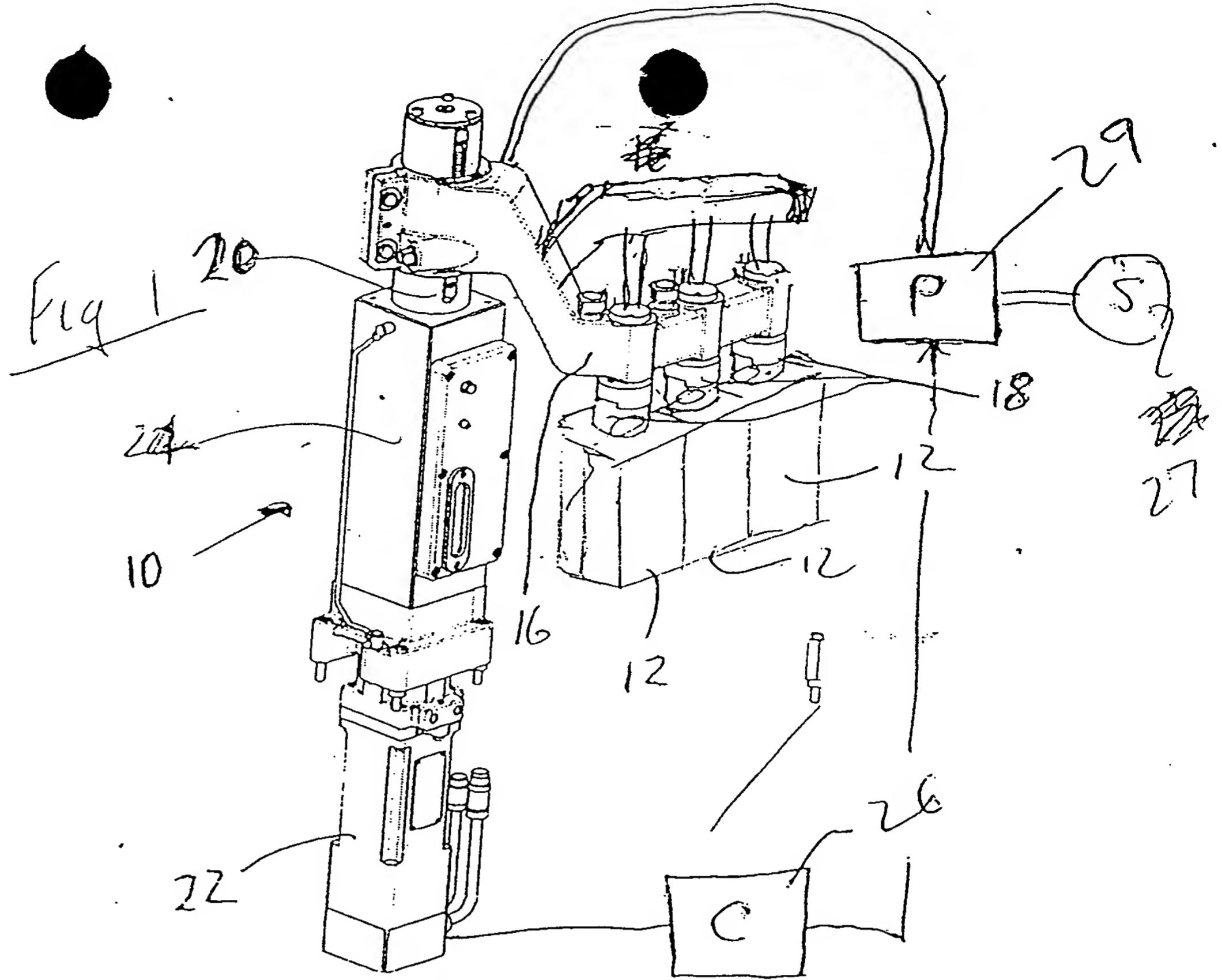
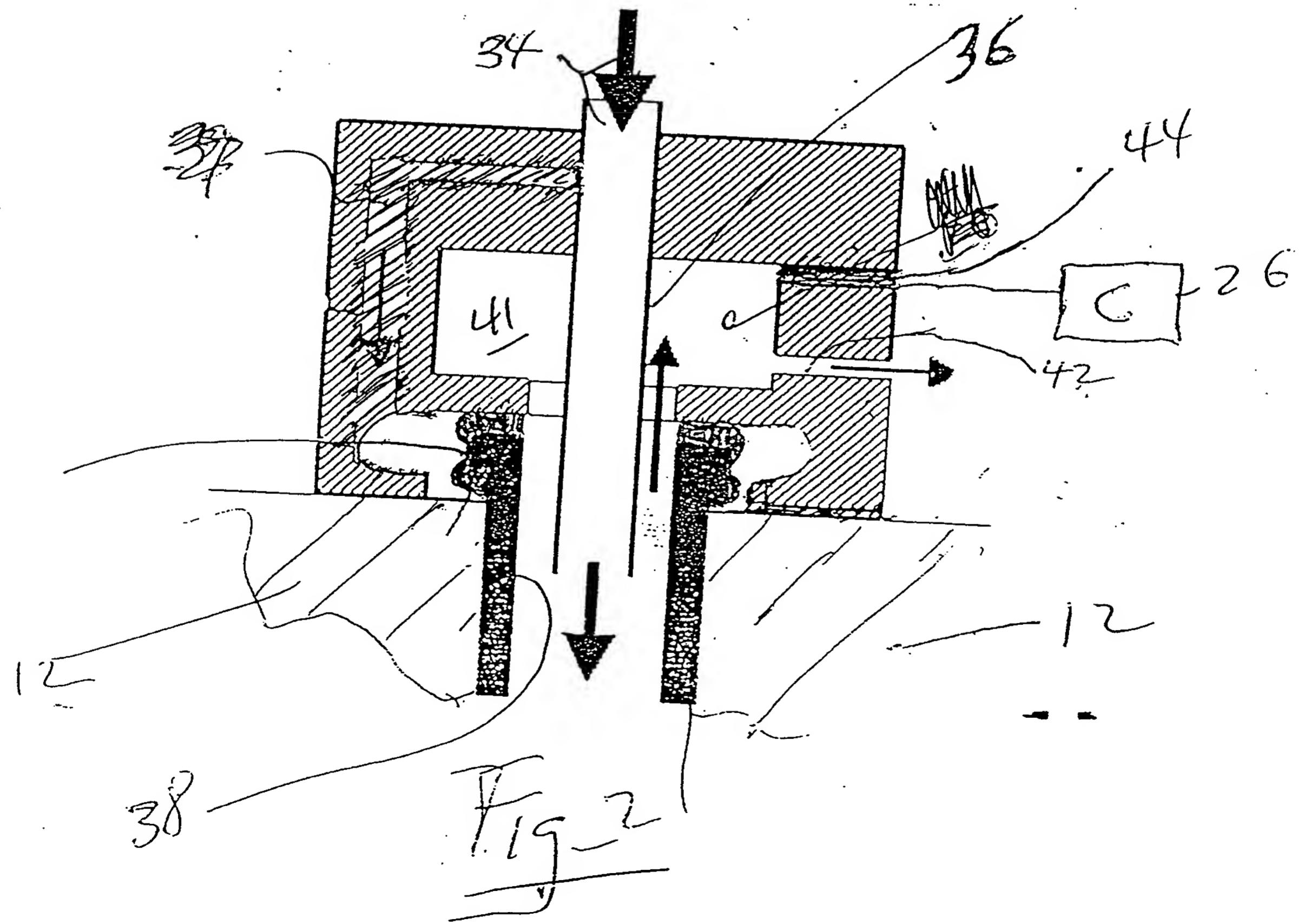


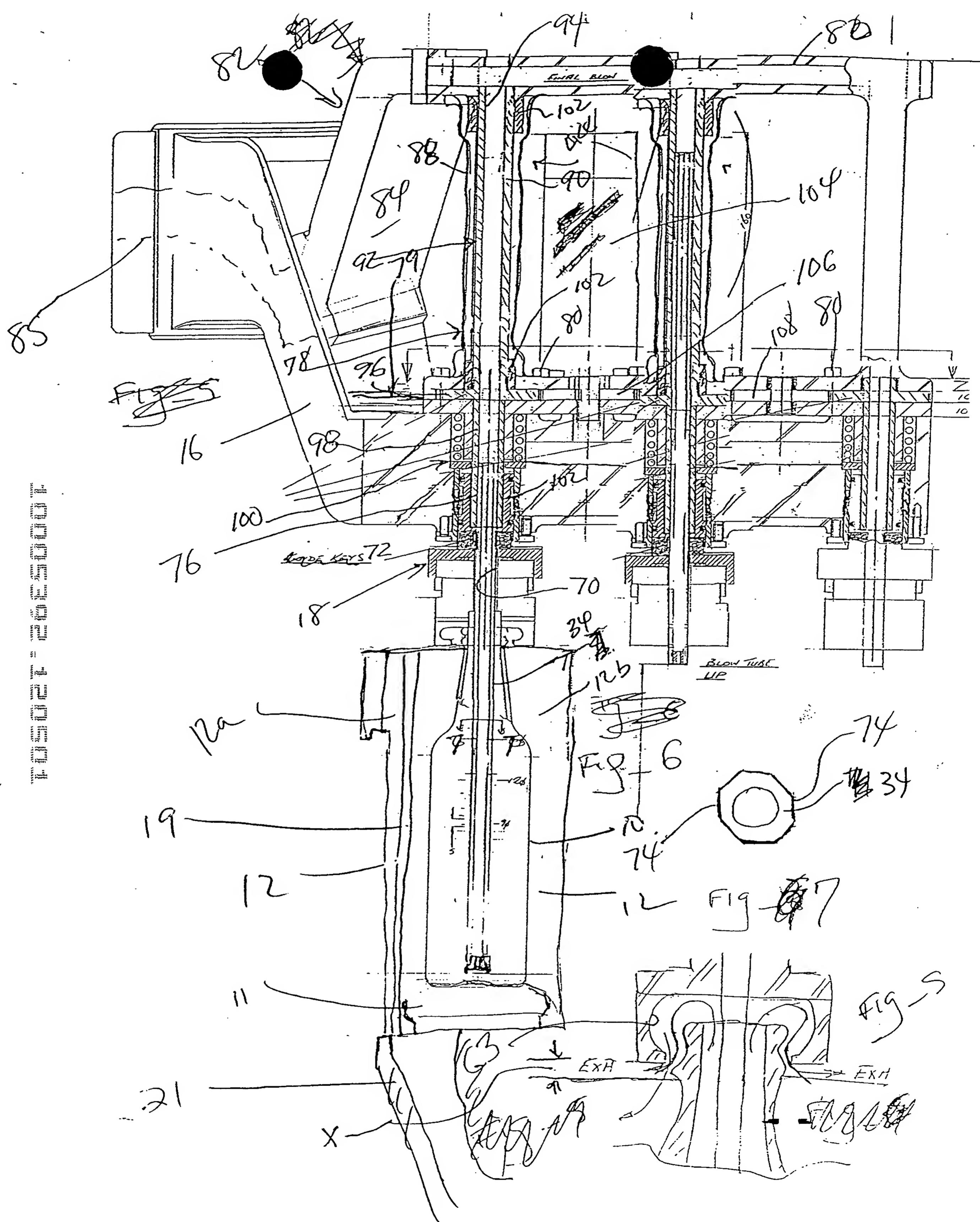
Fig. 1 20



40



F 11 20 01 24 T = 23 10 E 55 10 00 T



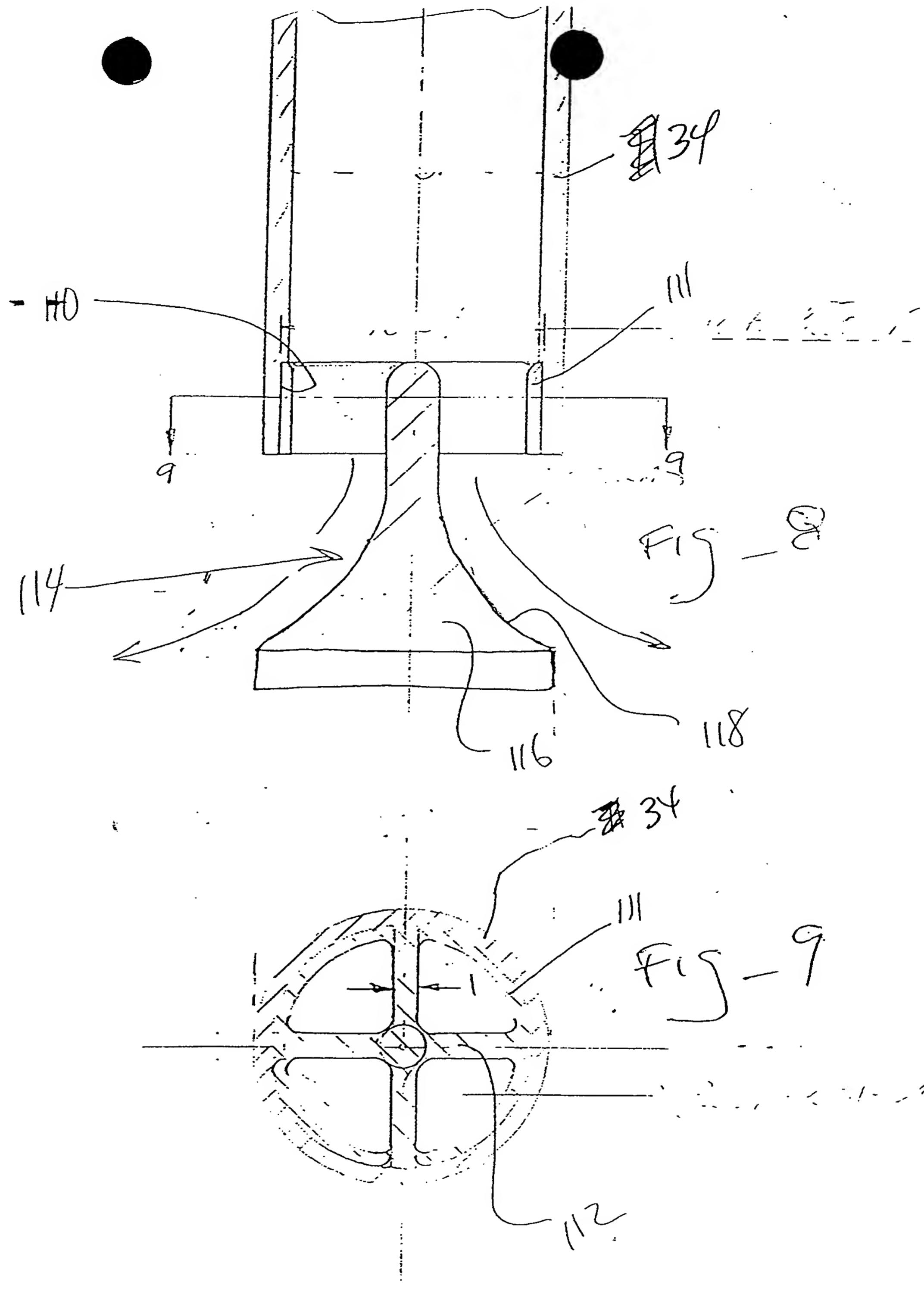


Figure 10

Fig - 10

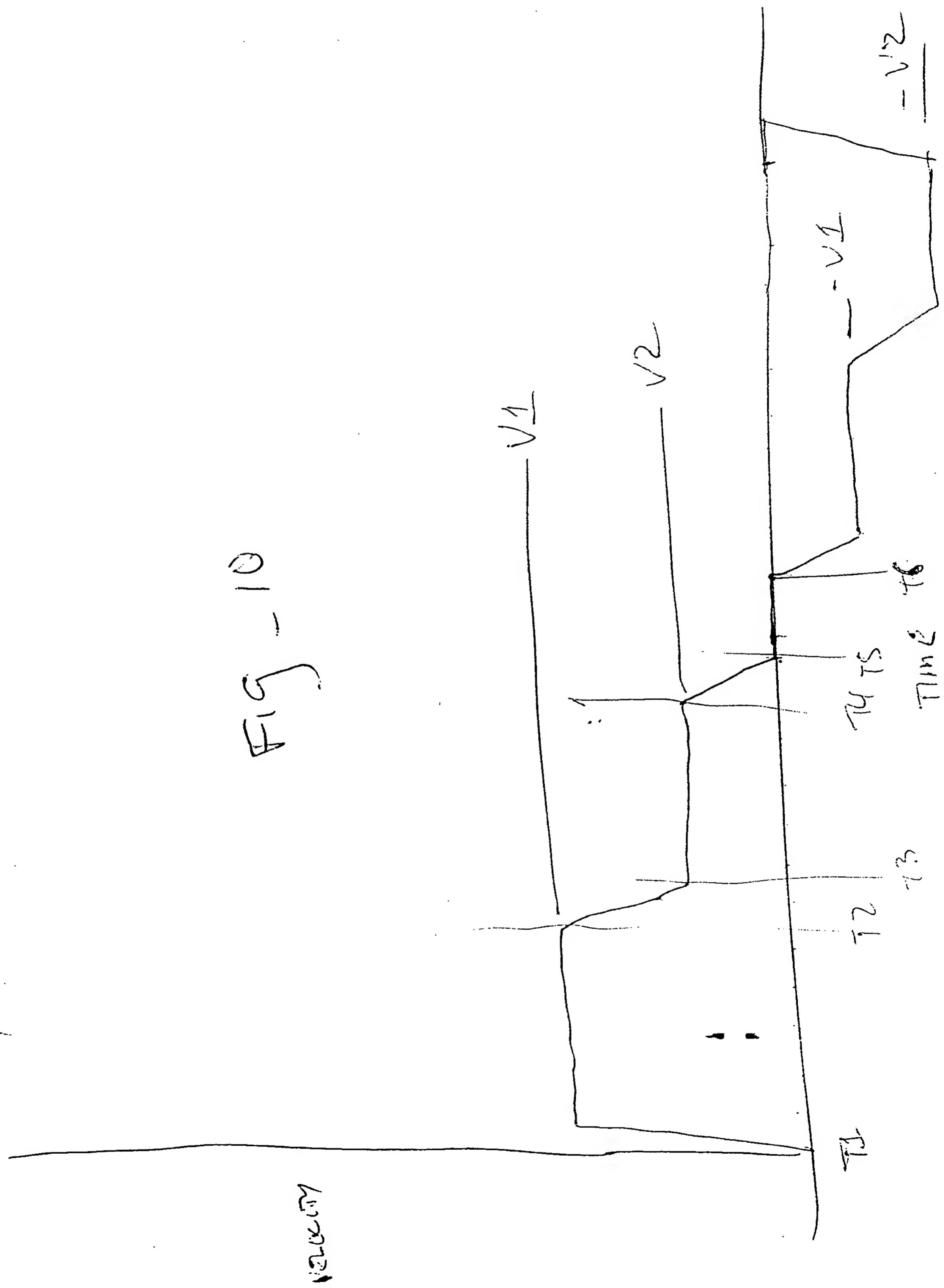


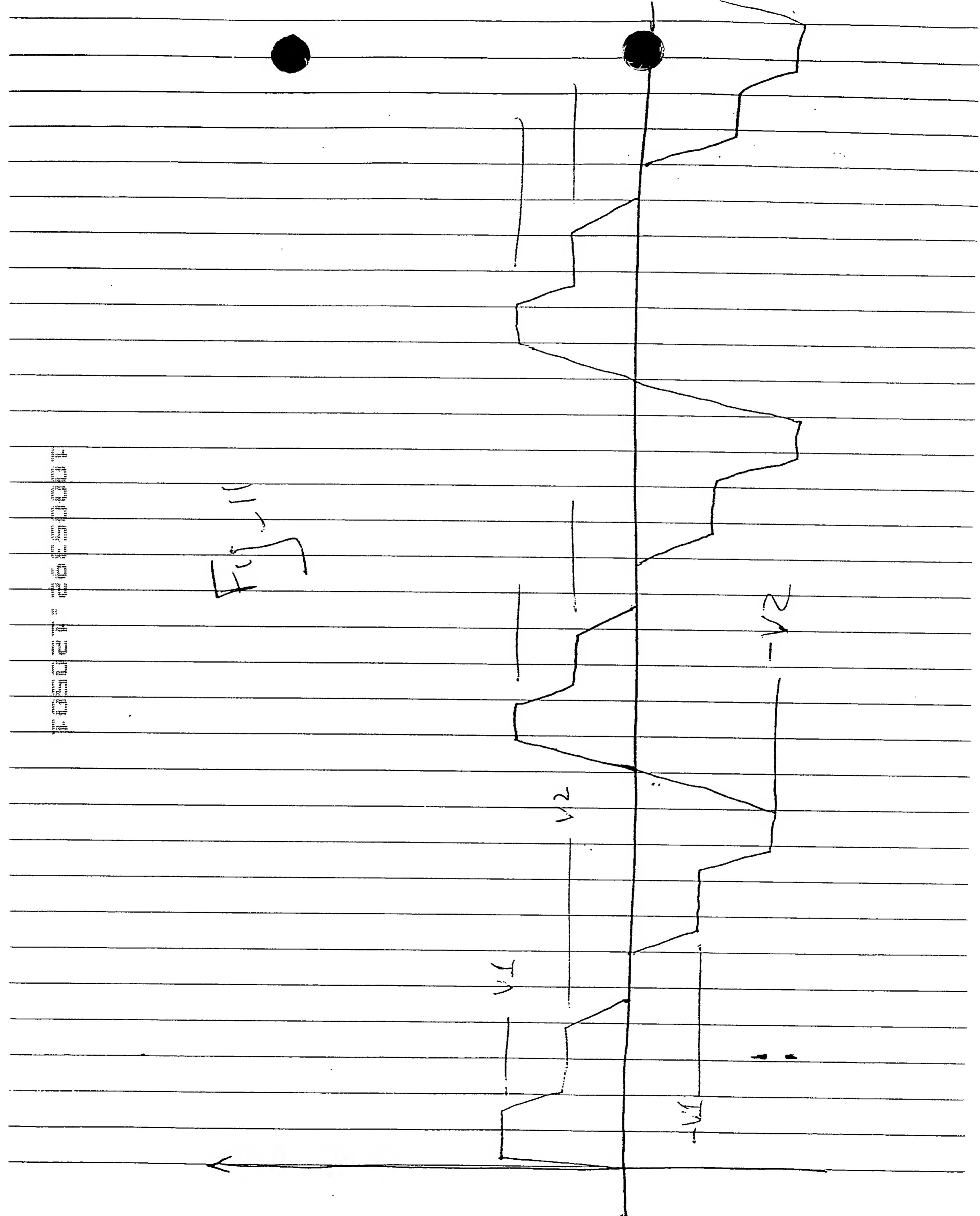
Fig. 11

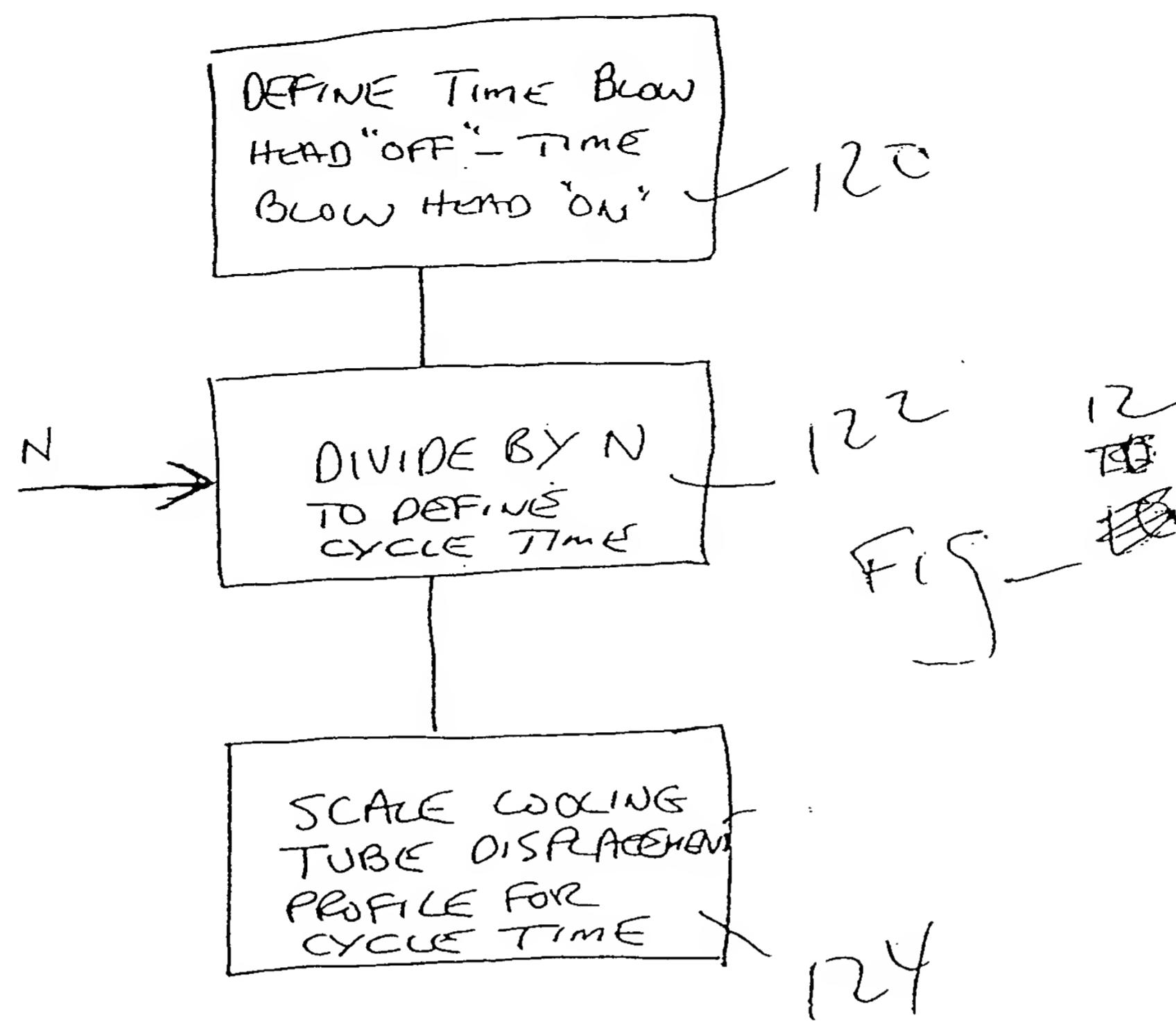
Fig. 11

v₂

v₁

v₁





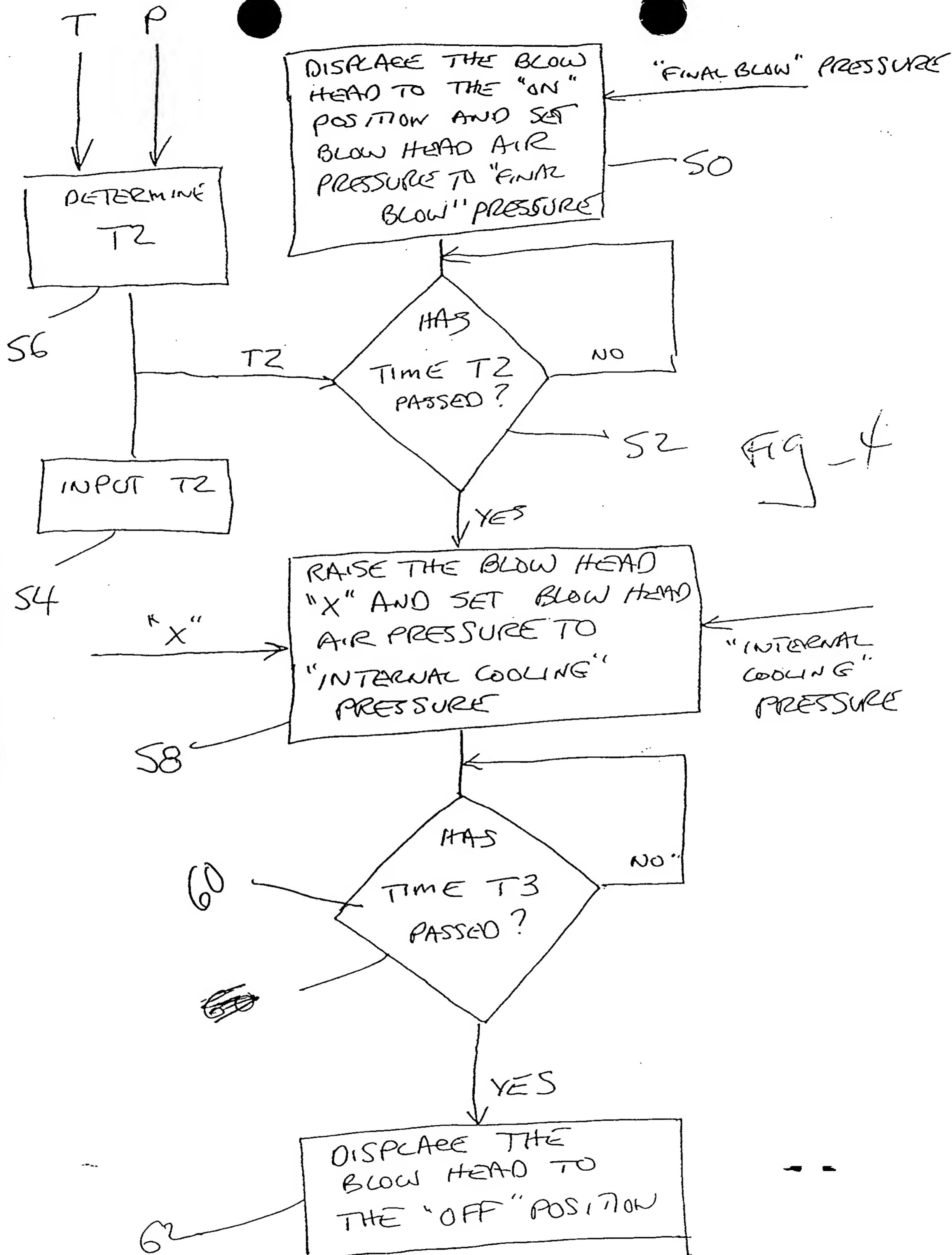
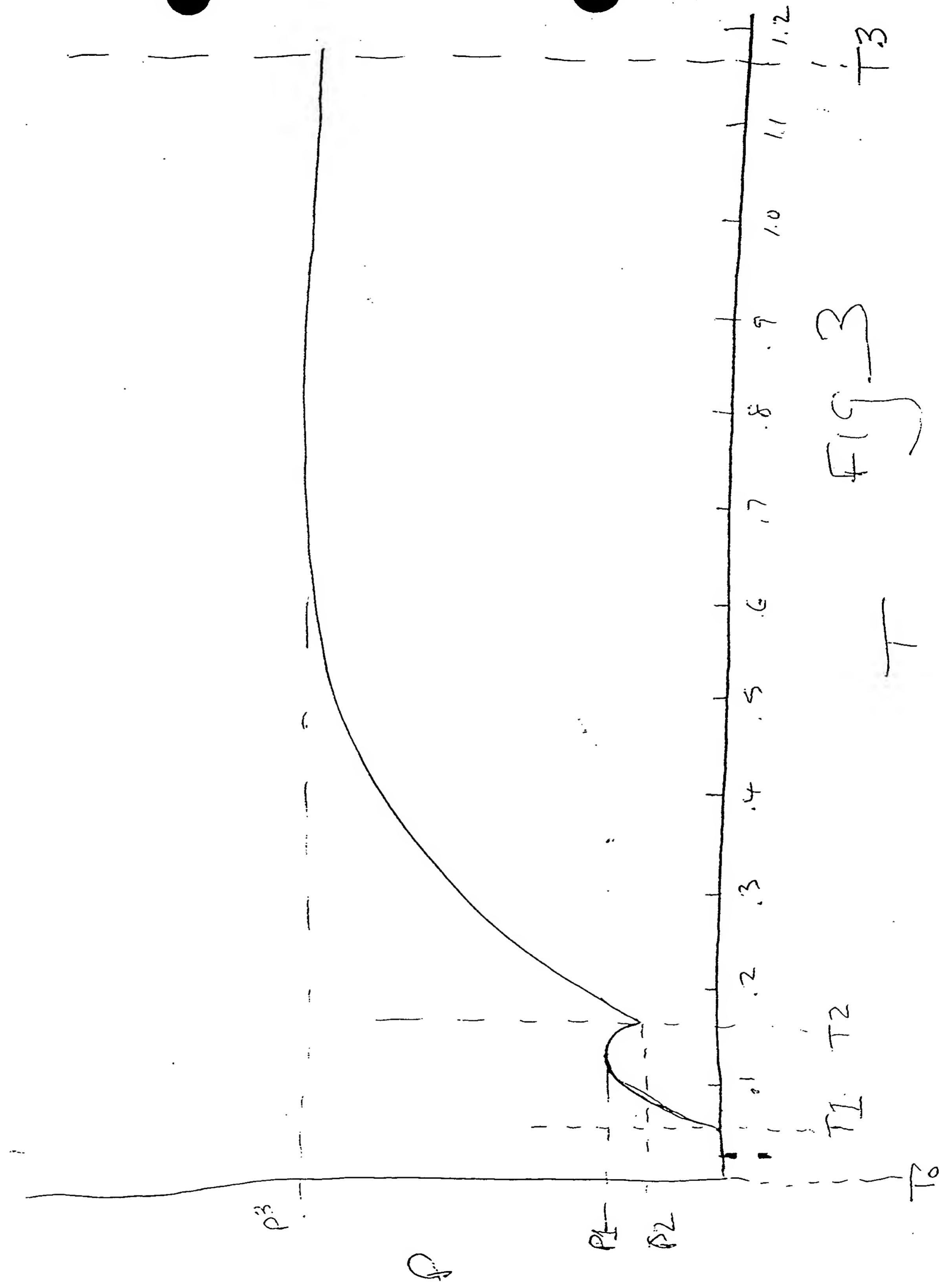


Fig. 3. A graph showing the variation of ρ with T .



1. 0 5 0 2 F = 2 2 2 E 2 0 0 0 0

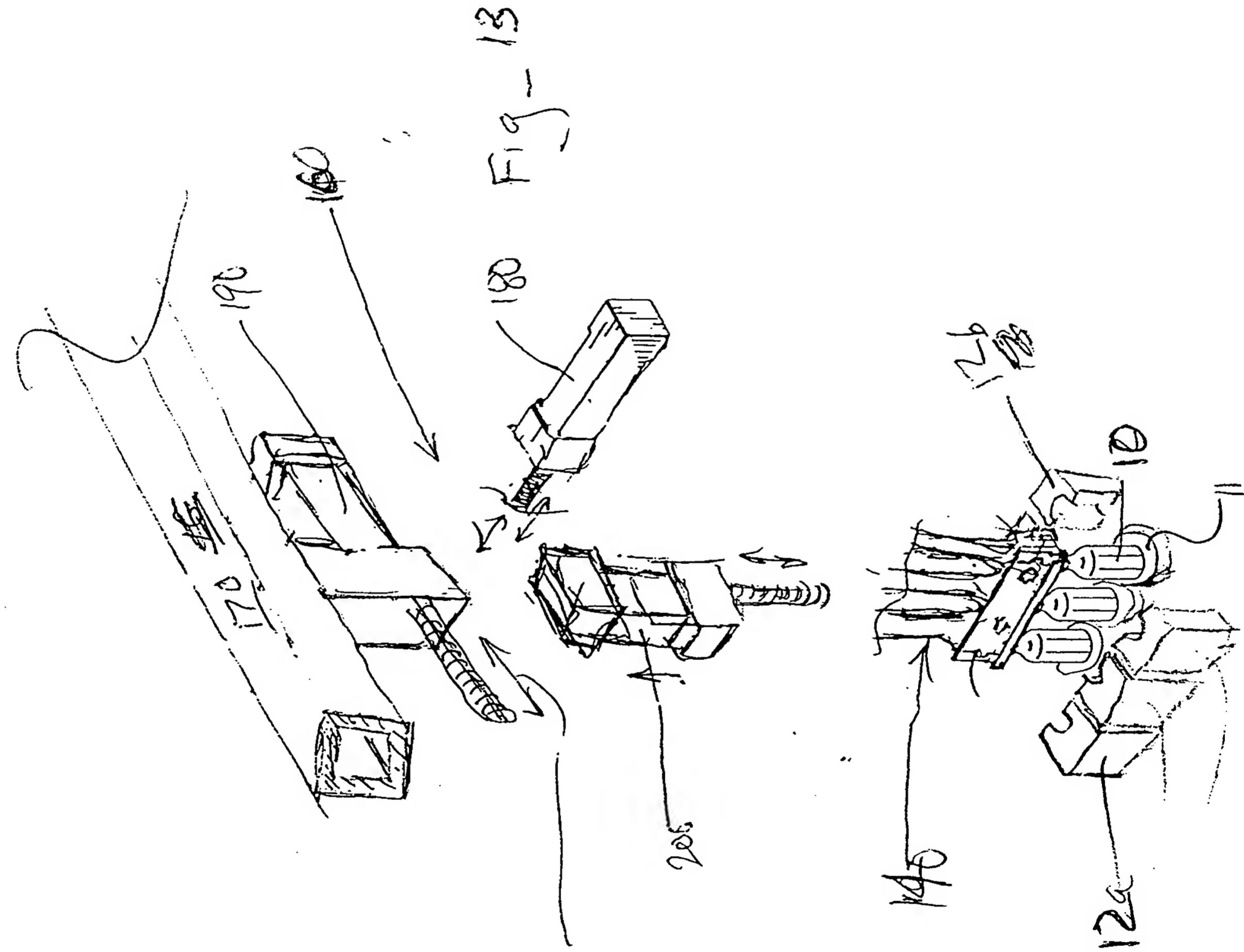


Fig - 13

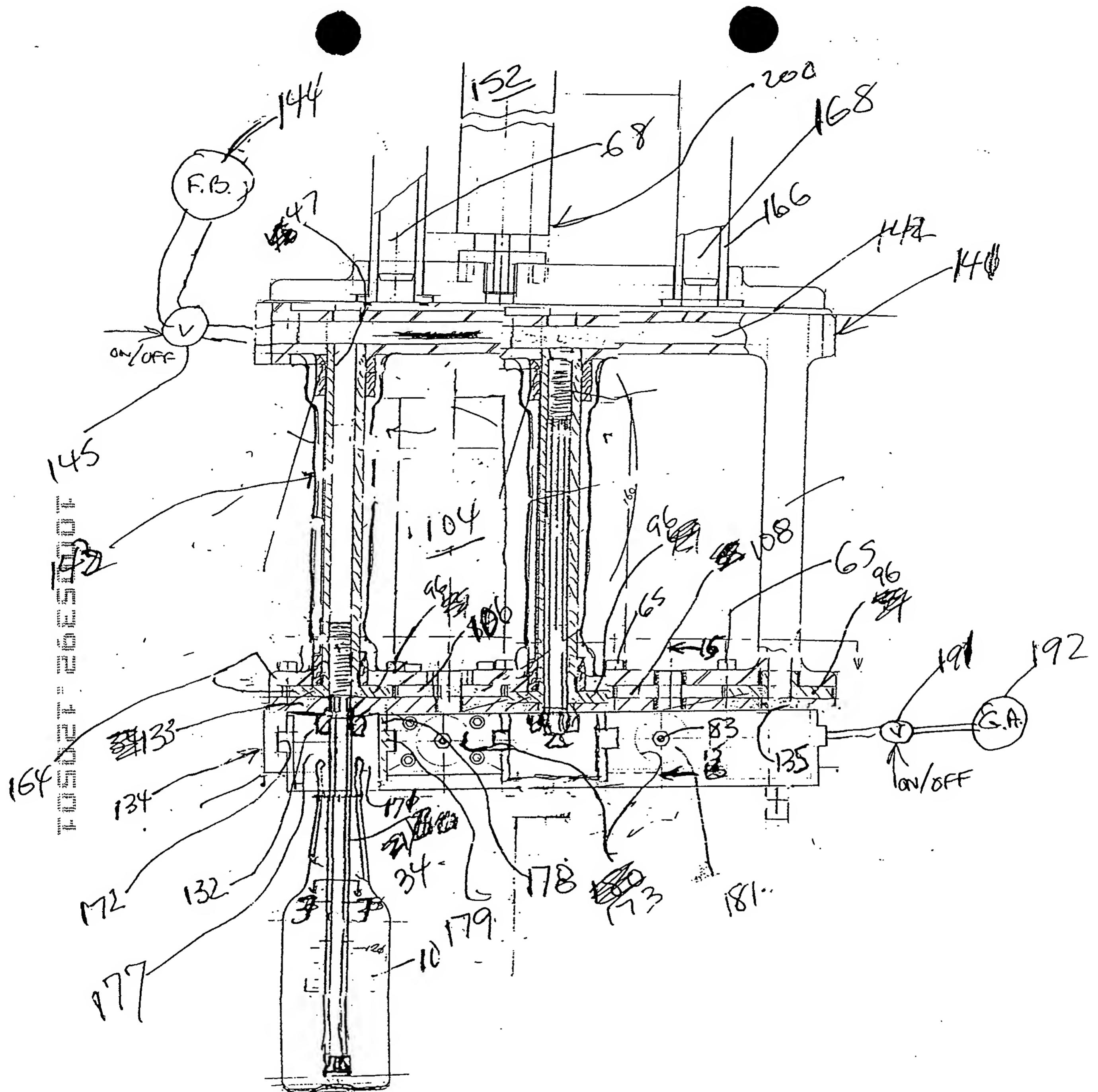
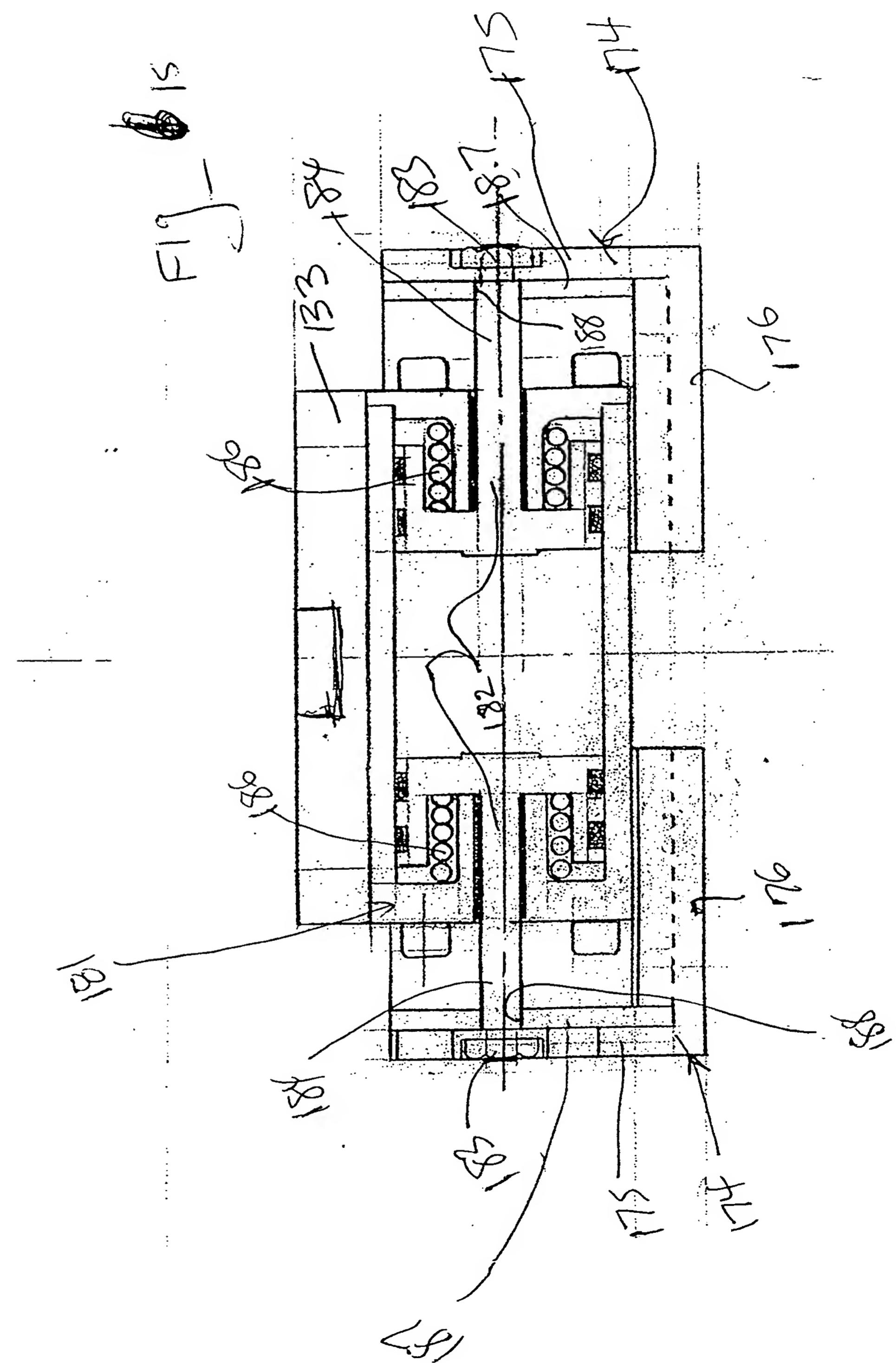


FIG - 14



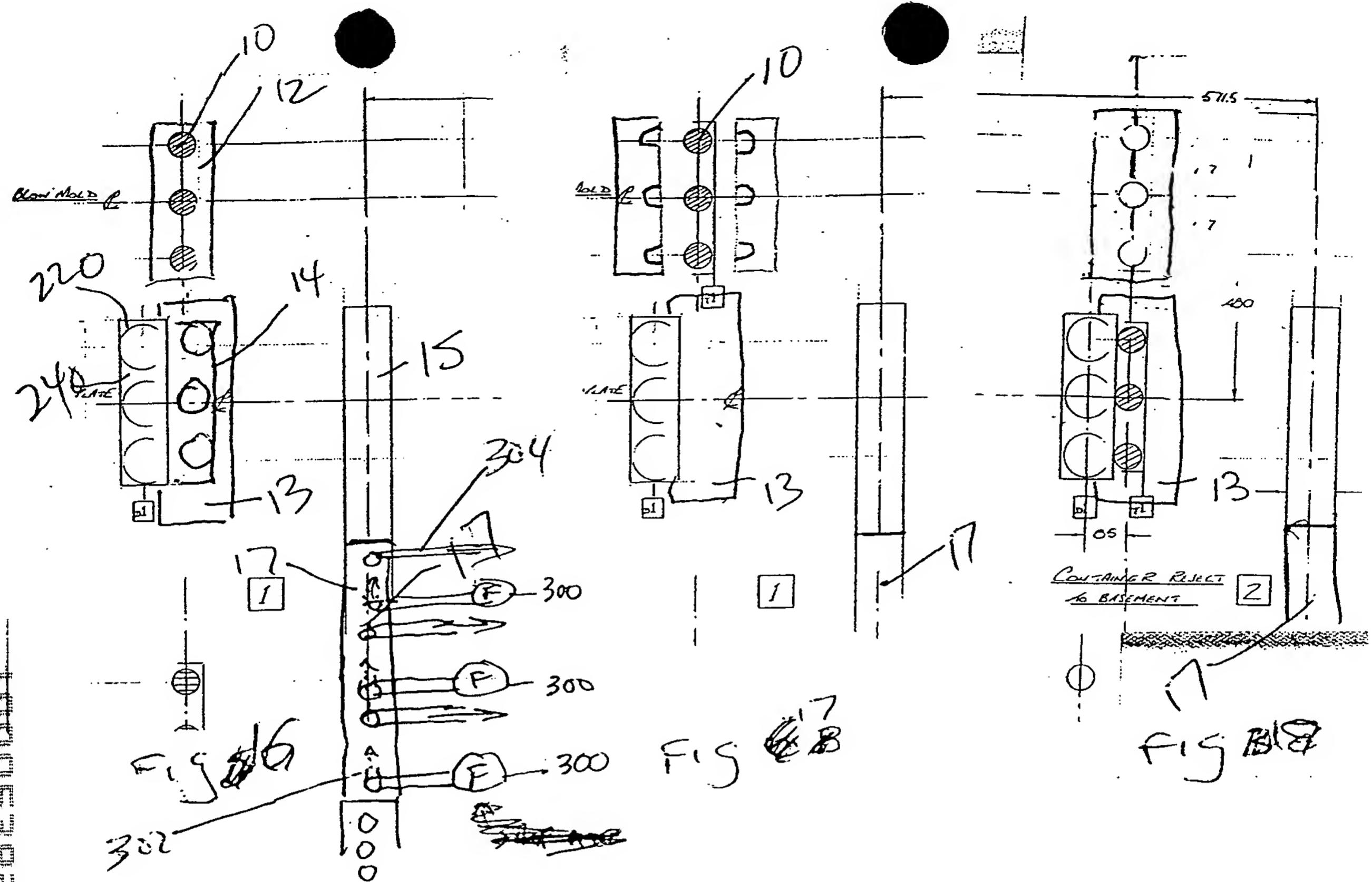
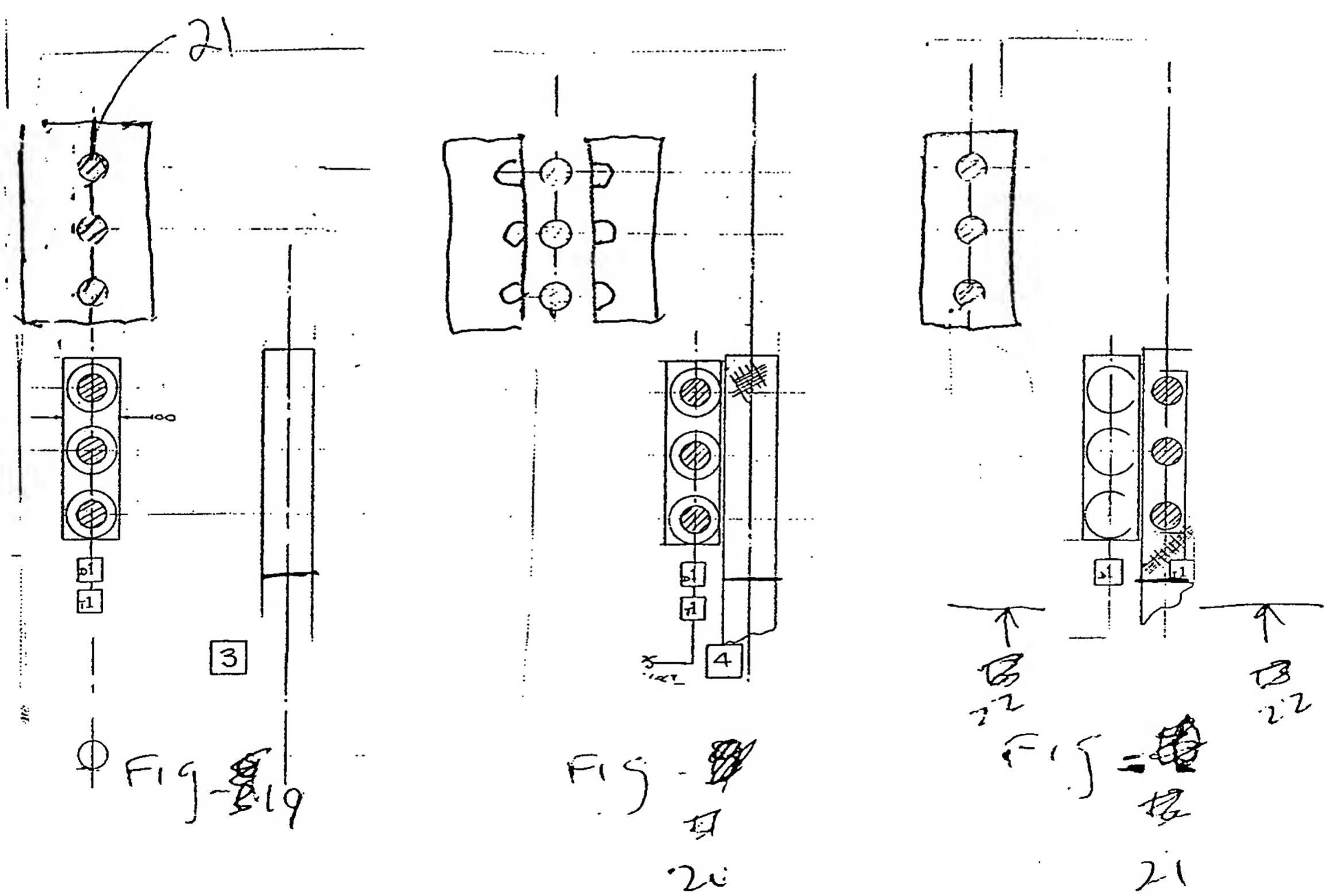


FIGURE 21

FIG. 21

FIG. 21



21

21

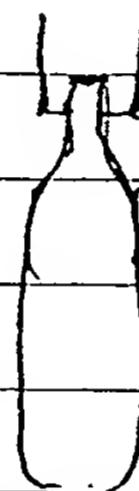
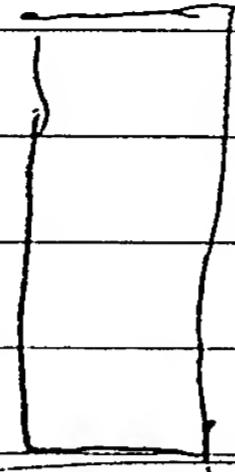
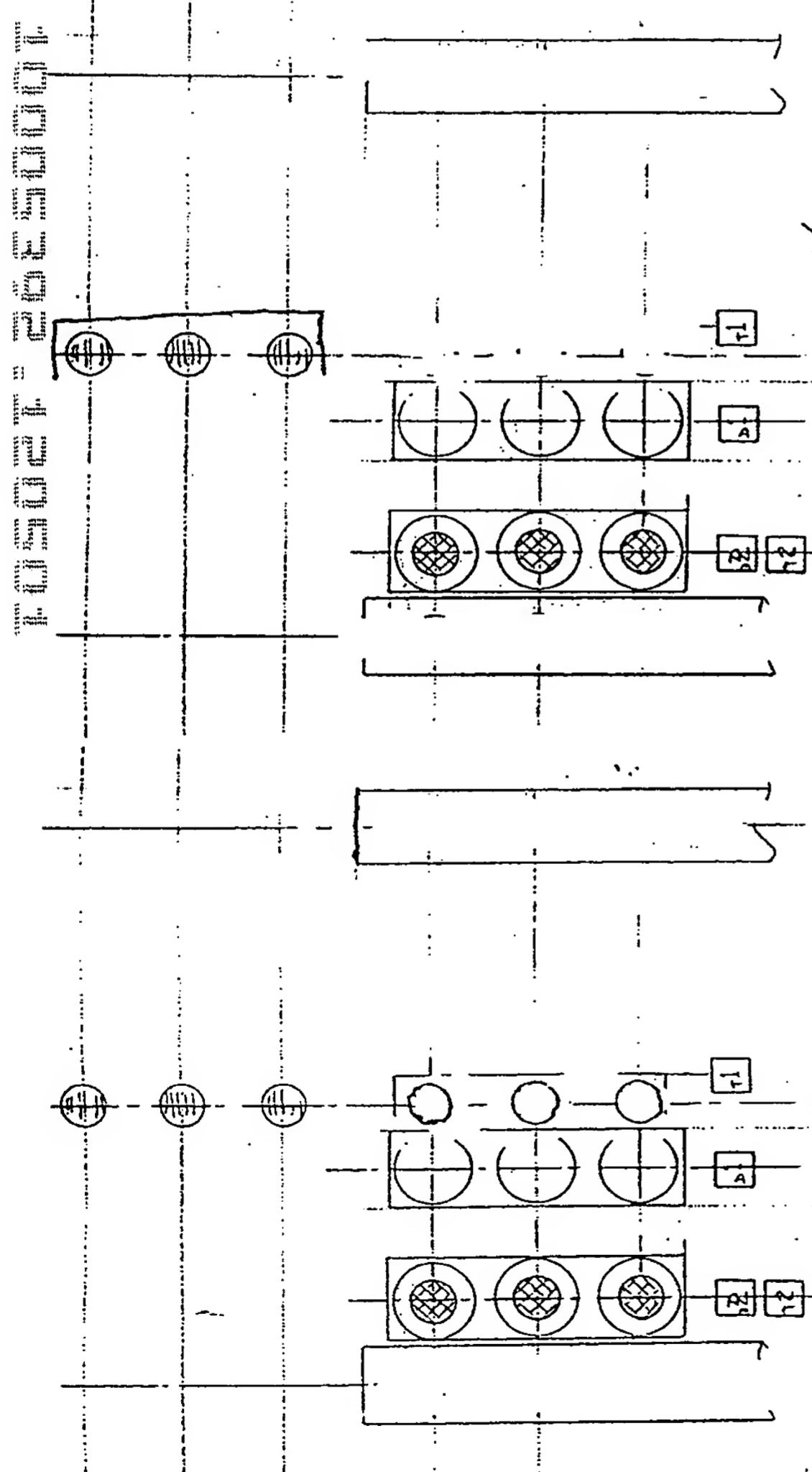
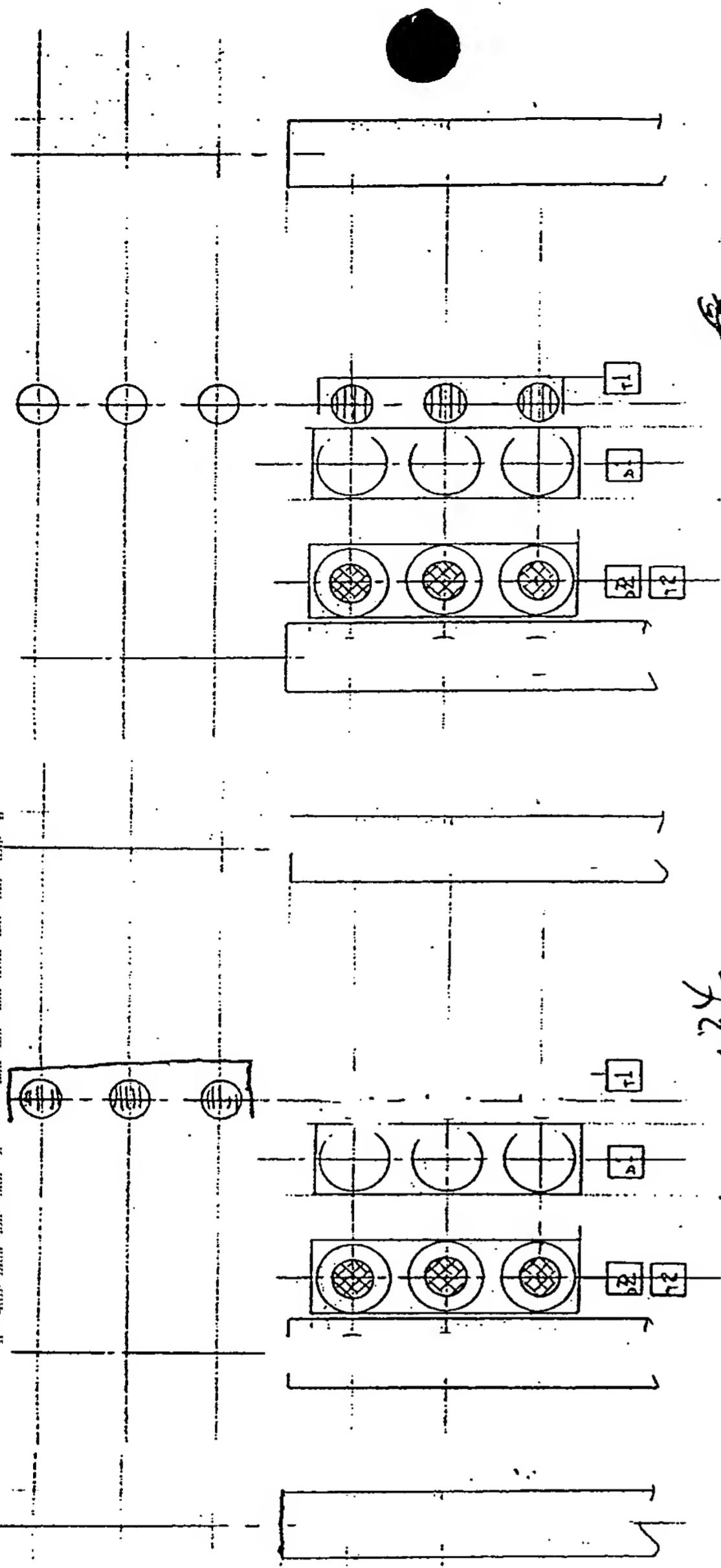


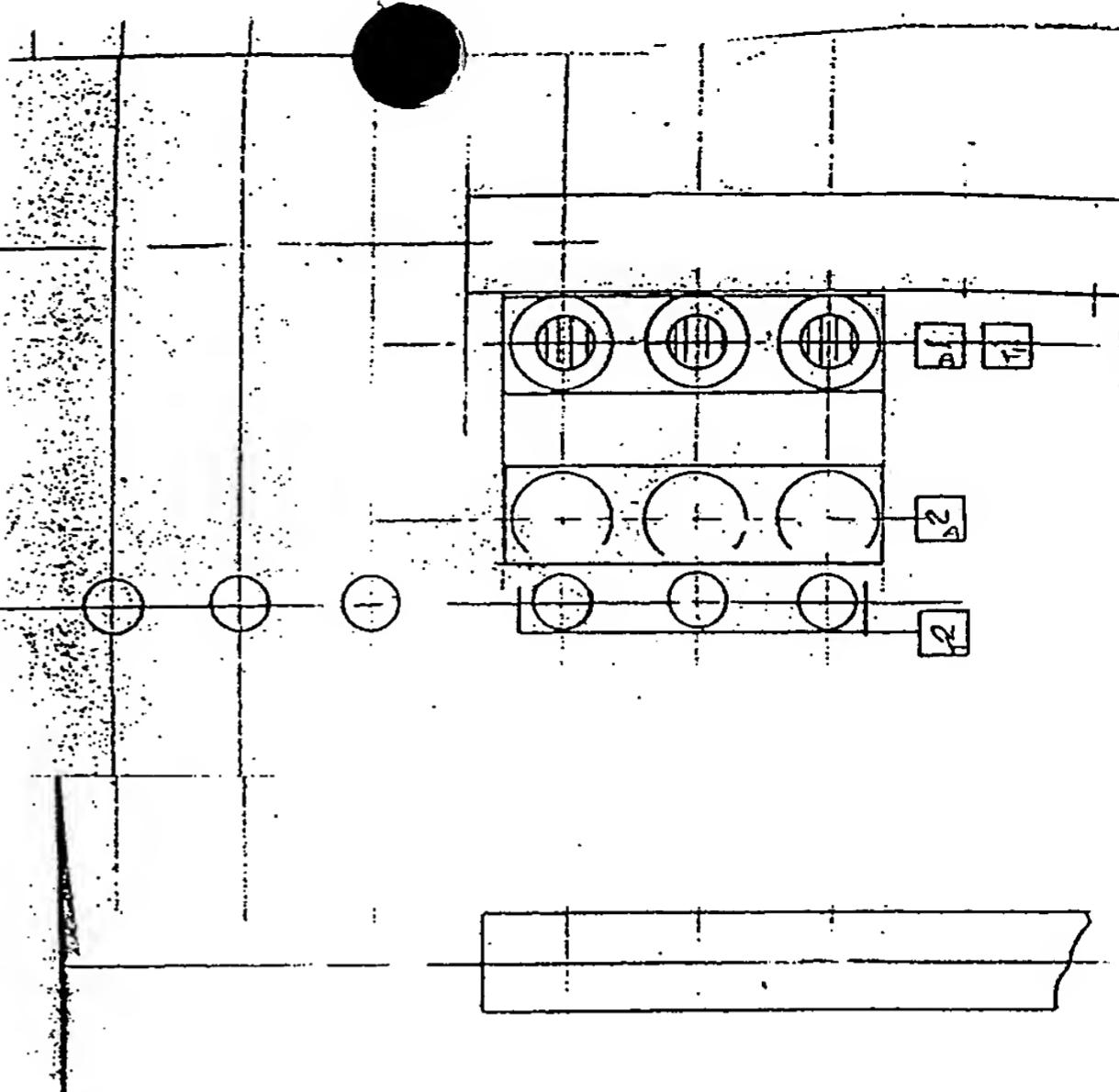
FIG 49 \$22



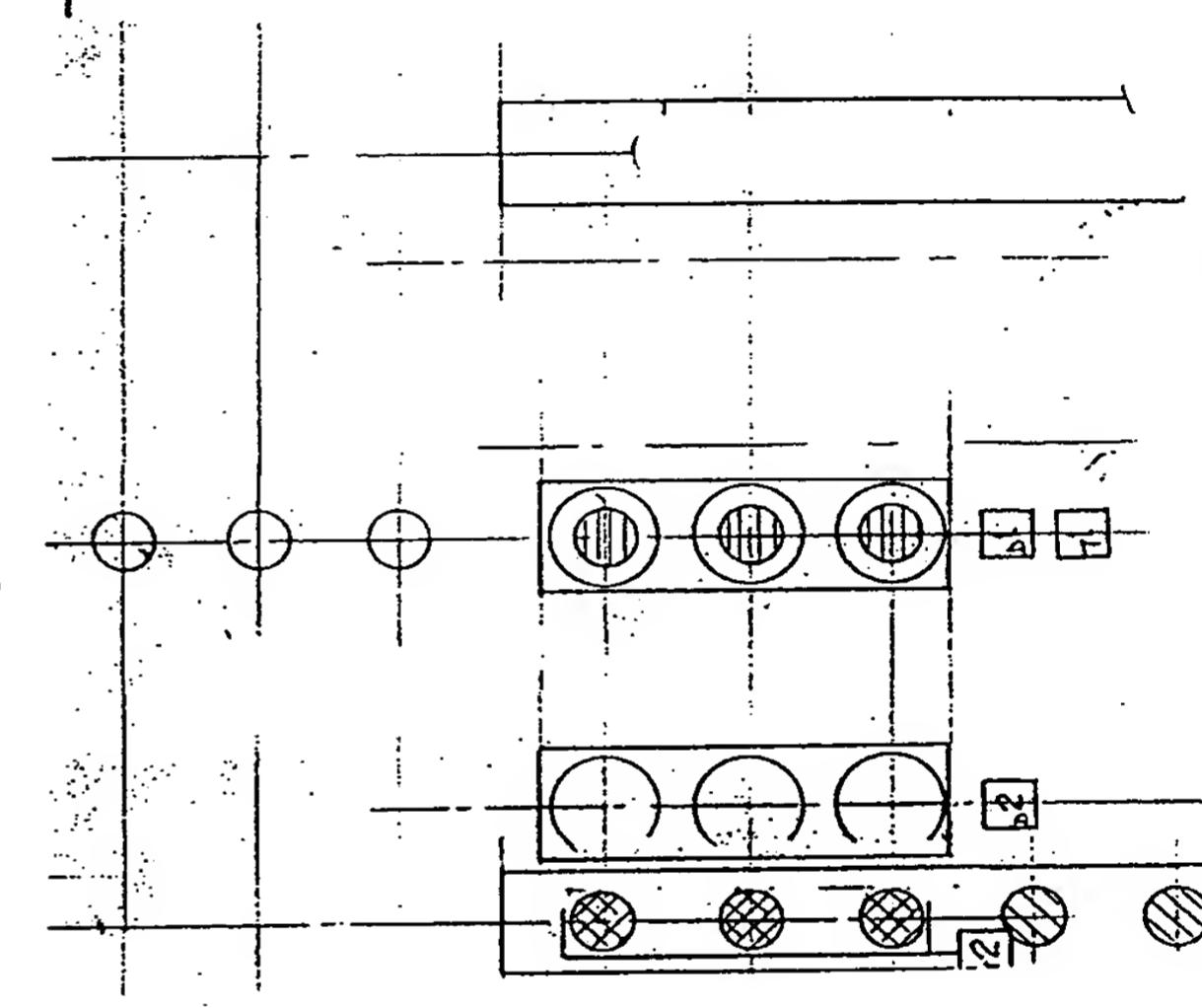
F(5) - 22



E^{ij} E^{jk} E^{ki}



卷之三



17

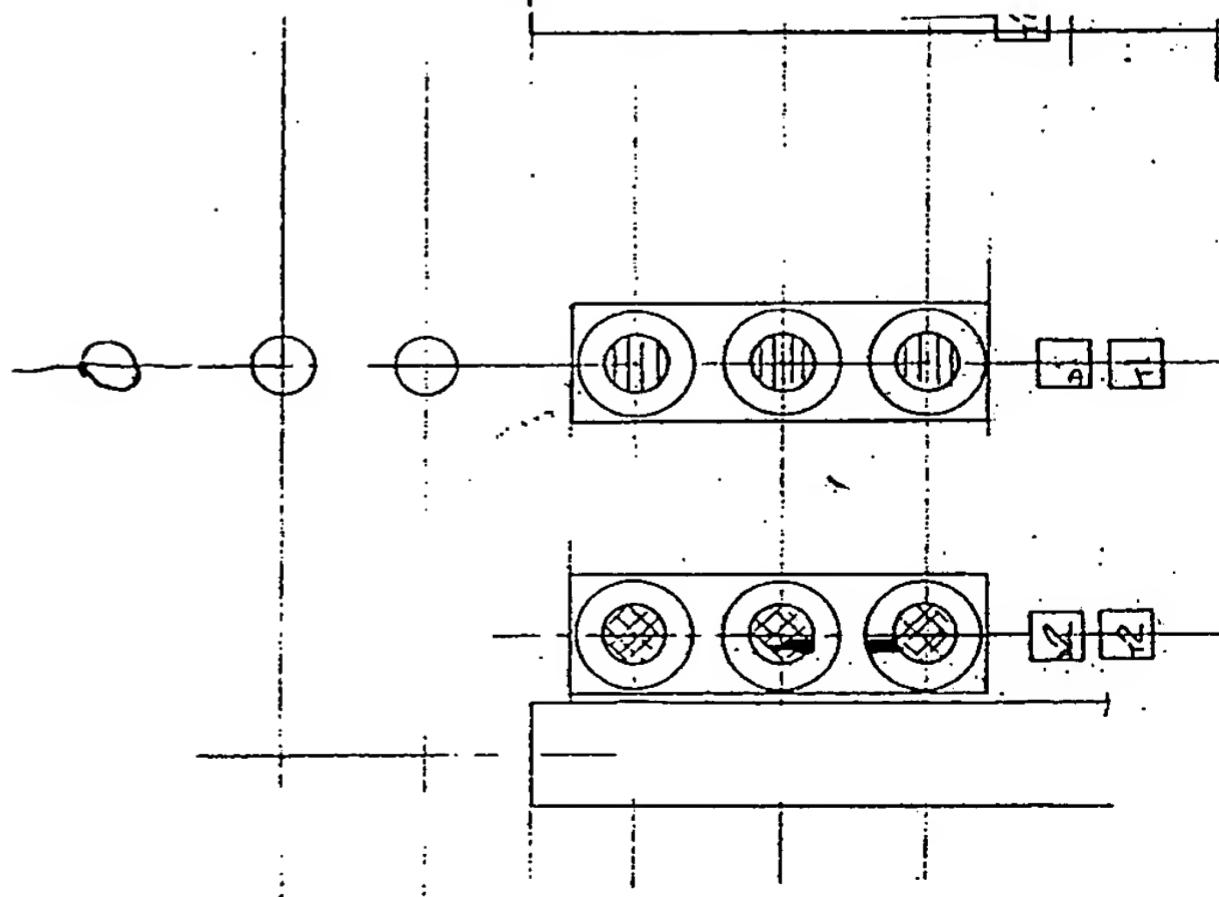
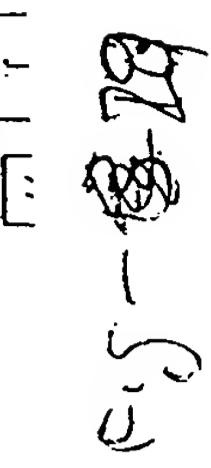
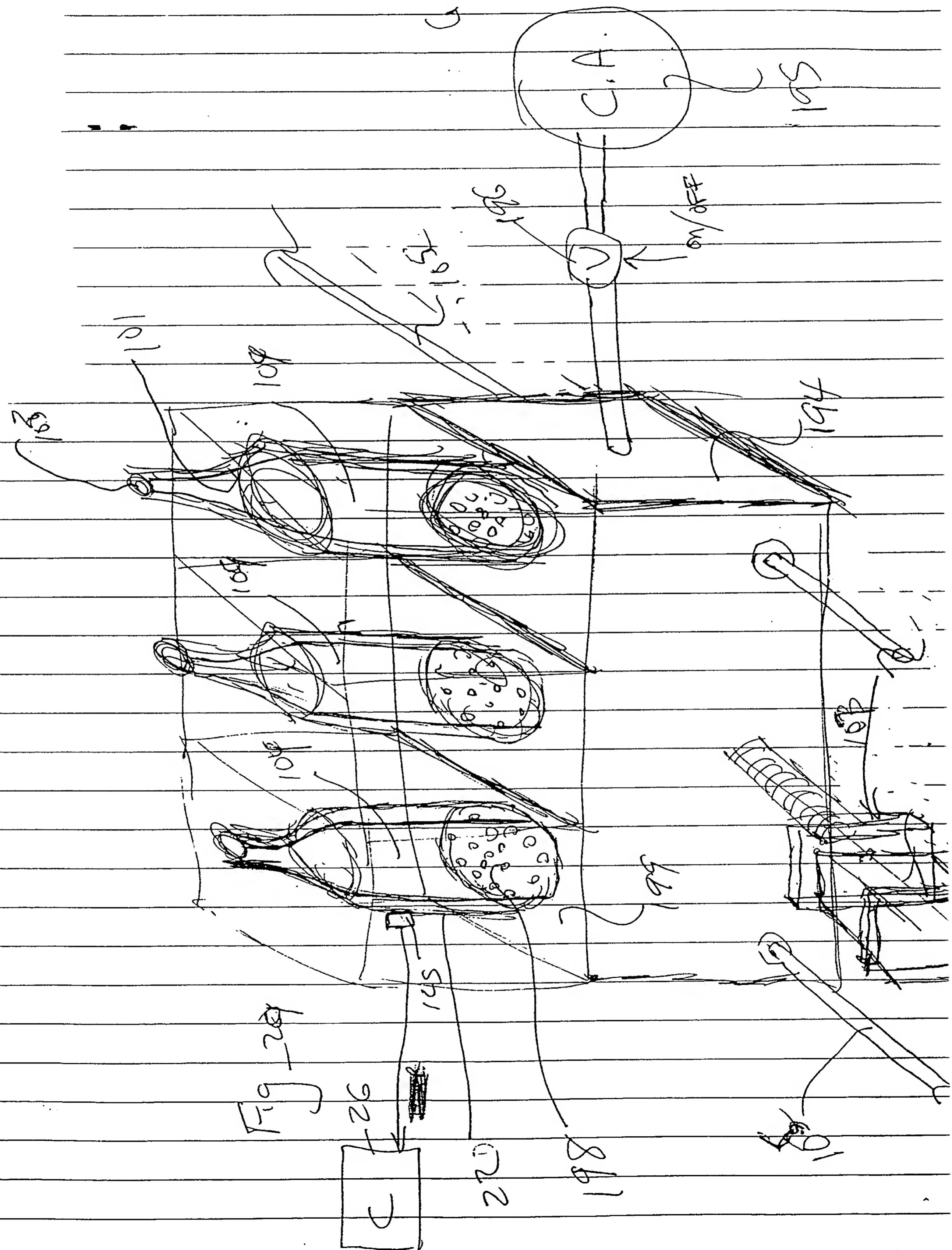
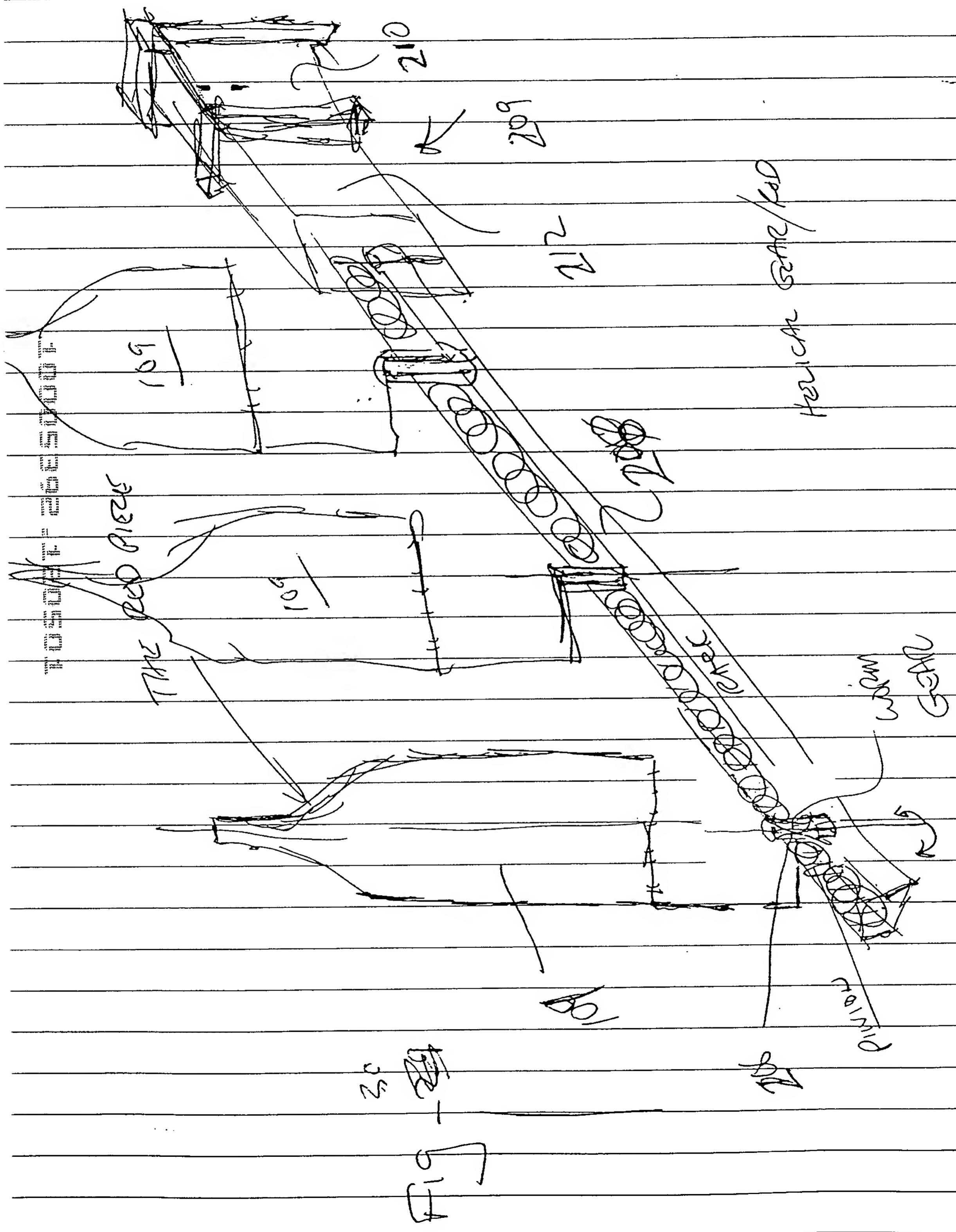


Fig. 1 - ~~Fig. 5~~ 26
17







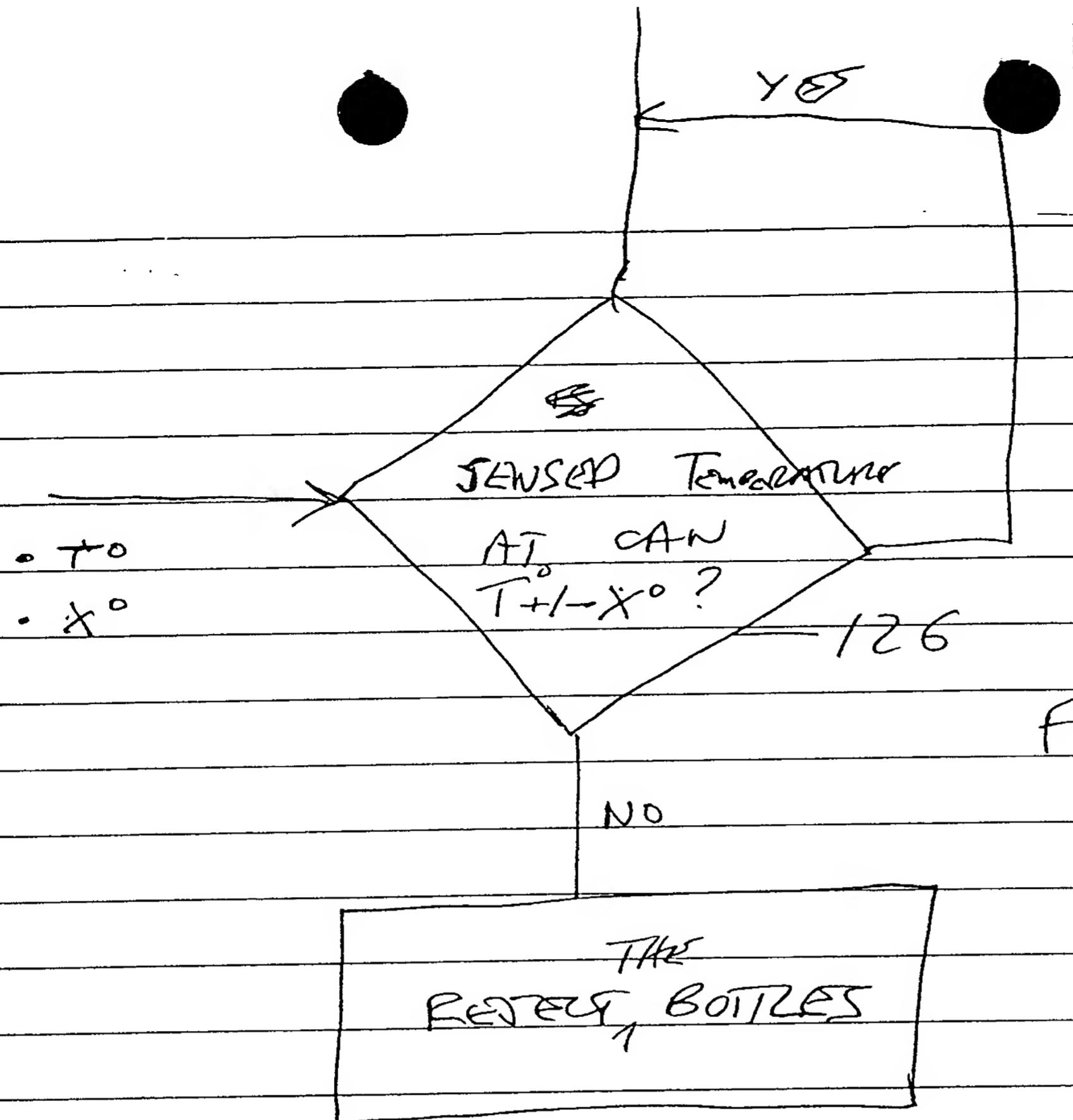


Fig - 31

TOE SLIP = SWELLING

F9 - 31

Brown friction

ANCHORING POINT

decoupling TUNER

TAKEDOWN ASSEMBLY
DENDROLOGY
MECHANISM

polymer
matrix

TAKE DOWN